Weighting Signal Error Reduction

Abdelkader Faris Abdelkader  
abdlkaderfares52@gmail.com

Fakhrulddin Hamid Ali  
fhazaa@uomosul.edu.iq

Computer Engineering Department, Collage of Engineering, University of Mosul

Received: 18/6/2020  
Accepted: 28/8/2020

ABSTRACT
The paper presents and discusses how to use some techniques to reduce the effect of error in the weighting signal which is produced from a load cell. The load cell is one of successful sensors which is used to transform the weight to an electrical signal. In industry the production of an accurate sensors suffers from a problem of noisy environment. Different source of noise like electromagnetic fields from motors, machines, power lines and microwave in addition to humidity and temperature variations have significant effects on weak electrical signals produced by load cells. Both hardware and software filtering are adopted to reduce the unwanted effects.

Keywords: Loadcell; Arduino; Differential signal; ADC converter; Instrumentation Amplifier

Copyright © 2020 College of Engineering, University of Mosul, Mosul, Iraq. All rights reserved.
https://rengj.mosuljournals.com
Email: alrafidain_engjournal1@uomosul.edu.iq

1. INTRODUCTION
In our time the industry world had seen great development and produce many products they need more development in the weight measurements such as asphalt industry and pharmaceutical industry there are group of sensors and transformers such as load cell used for the purpose of tracking and determining the accurate components of the objects during moving over conveyor belt [1] [2] as shown in figure (1).

The load cell sensor which is used for this purpose consists of strain gauges as sensing elements [3]. The strain gauge converts the deformation to electrical signal where the resistance variation in the strain gauge is proportional to the magnitude of the applied force [4]. In general the load cell consists of four strain gauges in a wheatstone bridge configuration to sense the weight. The wheatstonebridge achieves minimum possible deviation between the output and the ideal output voltage [5].

The load cell is used in many fields such as weighing measurement like food, fuel, cement, vehical, animals, gripper of robotic arm. The load cell produces a very weak signal in mille volt and makes it vulnerable to any out side unwanted signal such as noise, temperature vibration, electromagnetic interferences and high humidity effect. Some strategies has to be used to reduce the error in weighting signal. Because the output signal from load cell is very weak in mille-volt and we want to convert it to digital whereas the ADC input is in volt range. It is very necessary to use instrumentation amplifier to enlarge the signal and make it suitable for ADC. The instrumentation amplifier used in our system is AD620 its properties are low drift high gain and high CMRR[6] as shown in figure (3).

The signal after being amplified using instrumentation amplifier AD620 chip enter the arduino node mcu 32s it has internal ADC 12bit as shown in figure (3) [7] to convert it to digital. The digital output is varied as a result of noise affect. So it the output has a range from...
minimum to maximum range which needs to be reduced. So the output varies between minimum to maximum. This range of variations needs to be reduced.

2. Theory
Several measures have been conducted to reduce the noise effect some of them are stated in this article

2.1 Shielded Cables
One method to reduce the common mode electrostatic noise and prevents it from affecting the signal inside the cable by connecting one end of shield to GND in this case we prevent ground loop from forming.

2.2 Grounding
To ensure that all circuit in system has same reference potential we build a ground plane to reduce noise where every point on its surface is at the same potential. The ground plane makes low impedance ground fault return path to the power source where the analog ground is connected to the digital ground. In this method the ground noise effect is minimized [8].

2.3 Twisted Pair Cables
The same current flow in a pair in opposite direction so any noise add to the signal will add in both direction therefore one cancels each other[9]. In this way we reduce the effect of noise on the signal as shown in figure (2).

2.4 Wire Routing
This technique is used in order to keep high voltage power and motor wiring noise from affecting low voltage signal wiring. Which is done by separating low voltage wires from high voltage wires through free air using tray dividers. It is essential for keep signal integrity [2]. This is important when using the system in industrial environment.

3. Previous Work
Since the need to pay attention to the signal which is produced from the Load cell and reduces its error resulting from the noise, the researchers began proposing and presenting ideas to reduce the noise, and from a set of previous ideas, some suggestions and actions are reviewed.

P. Castellini (2002) proposed the “Anti-Aliasing Filter”. This filter removes noise at frequencies above the anti-aliasing filter cutoff frequency. The cutoff frequency can be determined by the sample rate for a data acquisition system which is twice the maximum frequency of interest according to the Nyquist sampling theorem. Anti-aliasing filters can be implemented in software using over sampling [1].

Kyoo Nam choi (2011) proposed ”Variable cutoff frequency and slope LpF” which consisted from two stage the first stage is L.P.F for cutoff frequency variable to reject peak noise components the next stage is six lpf for slope control and obtaining pulse width ratio during the remove of un wanted noise spectrum[2].

RajeshDey, AtreyeeBiswa Suman kumarLaha ,Amlan pal and DR. Achintya Das (2014) proposed the “Signal Correction of load cell output using Adaptive Method” that consists of no.of stages the first stage has two missions they are producing mathematical model of a load cell and takes digitized output of load cell by entering to ADC. The adaptive techniques minimize the oscillation in output and also from the digital data converted to analog by DAC [10].

John frank (2017) present” weight controller equipped with analog low _pass
filter”. The Lpf removes random jitter and produces analog averaging close to the original signal. The mission of weight controller equipped with adual _slope, ADC, is digitizing the signal and takes the average for the readings and produces smooth signal [4].

4. Proposed and implemented work
A simple block diagram of the current system is illustrated in figure (3).

![Figure (3). Schematic of basic system block diagram.](image)

As the beginning, the load cell must be checked which is used in the current system if it is linear or non linear. By applying the loads from 100g to 20kg and record the output voltage from Load cell using digital voltmeter with high accuracy (two digits after decimal in millivolt range).

![Figure (4) Load cell linearity.](image)

After the linearity test of the used load cell the over all system is tested and its output is measured at different loads according to the flow chart given.
4.1 Different Load Test
The first test is carried out using different loads from 1kg to 10kg. The net weight is measured by subtracting the no load weight from the total weight. The digital readout is multiplied by a factor to transform it into weight in gram. The weight factor (WF) is computed to be between 6.15 and 6.2 as shown in figure (6).

Table 4.1: The weight by using weight factor (WF)

<table>
<thead>
<tr>
<th>Loading (kg)</th>
<th>Average (Kg)</th>
<th>Factor</th>
<th>END weight (g)</th>
<th>Combined Error</th>
</tr>
</thead>
<tbody>
<tr>
<td>1000g</td>
<td>159.0871</td>
<td>6.15</td>
<td>986.2388 (g)</td>
<td>1.8772%</td>
</tr>
<tr>
<td>2000g</td>
<td>318.0527</td>
<td>6.22</td>
<td>1961.5252 (g)</td>
<td>2.0084%</td>
</tr>
<tr>
<td>3000g</td>
<td>476.1150</td>
<td>6.29</td>
<td>2949.126 (g)</td>
<td>2.6058%</td>
</tr>
<tr>
<td>4000g</td>
<td>644.7440</td>
<td>6.22</td>
<td>3964.3992 (g)</td>
<td>0.8815%</td>
</tr>
<tr>
<td>5000g</td>
<td>813.9996</td>
<td>6.12</td>
<td>5054.2533 (g)</td>
<td>1.0835%</td>
</tr>
<tr>
<td>6000g</td>
<td>983.6610</td>
<td>6.06</td>
<td>6067.4501 (g)</td>
<td>1.7241%</td>
</tr>
<tr>
<td>7000g</td>
<td>1146.6690</td>
<td>6.10</td>
<td>7072.5299 (g)</td>
<td>1.0421%</td>
</tr>
<tr>
<td>8000g</td>
<td>1307.8080</td>
<td>6.11</td>
<td>8066.873 (g)</td>
<td>0.8359%</td>
</tr>
<tr>
<td>9000g</td>
<td>1475.0990</td>
<td>6.09</td>
<td>9102.4224 (g)</td>
<td>1.3385%</td>
</tr>
<tr>
<td>10000g</td>
<td>1642.3020</td>
<td>6.09</td>
<td>10190.1229 (g)</td>
<td>1.30112%</td>
</tr>
</tbody>
</table>

(Combined error is over all error). (Accurate weight is the weight that results from operation of handling and removing the error from the signal which produced from Load cell after applying the load on it and its near by that load).

Figure (6). Using the weight factor only.

4.2 Adaptive Weight Factor (AWF)
To further decrease the effect of error, each load is multiplied by the required factor to eliminate the error and the outcome is illustrated in figure (7).

Figure (7). Error free factors
Case 1:
Where the scale, the electronic circuit, and the scale are outside the ground box, and we use a coaxial cable to transmit the weight signal and calculate the weight for the load that is 4kg as shown in figure (8) and figure (9).

Table 4.2: 4kg out Box.

<table>
<thead>
<tr>
<th></th>
<th>Average</th>
<th>Sigma</th>
<th>Max</th>
<th>Min</th>
<th>Weight(g)</th>
<th>Combined error</th>
<th>Improvement</th>
<th>% of readings</th>
</tr>
</thead>
<tbody>
<tr>
<td>Before Window</td>
<td>642.3548</td>
<td>8.830107</td>
<td>8.830107</td>
<td>500</td>
<td>3994.01</td>
<td>±0.149%</td>
<td>100000</td>
<td></td>
</tr>
<tr>
<td>After Window</td>
<td>692.3587</td>
<td>6.96689</td>
<td>722</td>
<td>52</td>
<td>3994.01</td>
<td>±0.149%</td>
<td>21.079%</td>
<td>100000</td>
</tr>
</tbody>
</table>

The combined error is calculated which is ±0.149% from the weight 3994.01g, also the average and the sigma improvement is 21.079%.

Figure (8). Out grounded box before window.

Figure (9). Out grounded box after window.

Case 2:
The same as case 1 but the electronic scale and the cct inside grounded box as shown in figure (10).

Table 4.3: 4kg inside grounded box.

<table>
<thead>
<tr>
<th></th>
<th>Average</th>
<th>Sigma</th>
<th>Max</th>
<th>Min</th>
<th>Weight(g)</th>
<th>Combined error</th>
<th>Improvement</th>
<th>% of readings</th>
</tr>
</thead>
<tbody>
<tr>
<td>Before Window</td>
<td>643.2382</td>
<td>12.45215</td>
<td>142</td>
<td>598</td>
<td>4000.23</td>
<td>±0.00575%</td>
<td>100000</td>
<td></td>
</tr>
<tr>
<td>After Window</td>
<td>643.2543</td>
<td>10.25584</td>
<td>734</td>
<td>605</td>
<td>4000.23</td>
<td>±0.00575%</td>
<td>18.195%</td>
<td>100000</td>
</tr>
</tbody>
</table>

The combined error is calculated which is ±0.00575% from the weight 4000.23 g, also the average and the sigma improvement is 18.195% as shown in figure (11) and figure (12).

Figure (10). Grounded box.

Figure (11). Inside grounded box before window.

Figure (12). Inside grounded box after window.
Case 3:

The same as case 2 but by using L.P.F as shown in figure (13) between instrumentation amplifier and ADC that is internal in the Arduino

![Figure (13). L.P.F [12].](image)

By using L.P.F.

![Figure (14).](image)

Table 4.4. 4kg by adding L.P.F.

<table>
<thead>
<tr>
<th>Average</th>
<th>Sigma</th>
<th>max</th>
<th>min</th>
<th>Weight(g)</th>
<th>Combined error</th>
<th>Sigma Improvement</th>
<th>% of change</th>
</tr>
</thead>
<tbody>
<tr>
<td>Before Filter</td>
<td>608.3002</td>
<td>1.721</td>
<td>804</td>
<td>88</td>
<td>4000.23</td>
<td>± 0.0057%</td>
<td>26.2%</td>
</tr>
<tr>
<td>After Filter</td>
<td>608.940</td>
<td>± 0.00055</td>
<td>724</td>
<td>594</td>
<td>4000.23</td>
<td>± 0.0057%</td>
<td>36.3 %</td>
</tr>
</tbody>
</table>

The combined error is calculated which is ±0.0057% from the weight 4000.23g, also the average and the sigma improvement is 26.2% as shown in figure (15) and figure (16).

![Figure (15). Using L.P.F. before window.](image)

![Figure (16). Using L.P.F after window.](image)

5. CONCLUSION

The proposed method is used to reduce the error in weighting signal. The error is produced from load cell. The algorithm computes the accurate average of the load applied on the load cell. In which the calculated average is assigned in to one of three ranges: upper limit, lower limit and middle. This paper is discusses many techniques to handle the error in weight signal. At the beginning the proposed system has used one factor for all loads, as an example 4kg is measured as 3964.5992g. After repeating the reading or the measurement 100000 times to calculate the average. The combined error is ± 0.885% which it means that the system requires another factor to enhance it. Piece wise linear factor or adaptive factor is built using software to perform additional reduction in the error of weight signal. The piece wise factor is slightly increases in the low range load such as 1kg then it will be medium value at middle such as 5kg. So at high range load the factor is slightly decreased. In case 1, the proposed system is out of the grounded box. For 4kg the weight is 3994.01g combined with error equal to 0.149% and the sigma improvement is 21.079% after reading 100000 samples to calculate the average. In case 2, the proposed system is contained inside grounded box, the resulting weight is 4000.23g combined with an error equals to ± 0.00575% and the sigma improvement is 18.195%. In case 3, the proposed system is contained inside grounded box and also low pass filter is connected. The weight is 4000.23g, containing an error equals to ± 0.00575% and the sigma improvement is 26.2% via reading 80000 samples to calculate average. In addition, in case 3, the system is reached to the accurate weight faster than other cases. The speed is shown by reduction in the time by about 20% compared with case 1 and case 2. This improvement is produced by using low pass filter which removed the noise in the high frequencies. The proposed method used the window to reduce the noise effect that is obvious from sigma value.

6. REFERENCES


تقليل الخطأ في الأشارة الوزنية

فخر الدين حامد علي
abdulkaderfares52@gmail.com

أعمال الموصل، كلية الهندسة، قسم هندسة الحاسوب

عطافار اسمر:
fhazaa@uomosul.edu.iq

جامعة الموصل، كلية الهندسة، قسم هندسة الحاسوب

الملخص

يقدم البحث ويناقض كيف يمكن استخدام بعض التقنيات لتقليل الخطأ في إشارة الوزن التي تنتج من خلية الحمل. خلية الحمل هي واحدة من أجهزة الاستشعار الناجحة التي تستخدم لتحويل الوزن إلى إشارة كهربائية. في الصناعة، يعاني إنتاج إشارة دقيقة من مشكلة كبيرة في بيئة مليئة بالضوضاء، حيث أن مختلف مصدر الضوضاء المختلفة مثل المجالات الكهرومغناطيسية من المحركات والآلات وخطوط الطاقة والموجات اللاطيفية بالإضافة إلى الرطوبة وتغيير درجة الحرارة له تأثيرات كبيرة على الأشارات الكهربائية الصعبة التي تنتجها خلية الحمل تم استخدام كل من الفلتر والبرامج لتقليل التأثيرات غير المتوقعة.

الكلمات الدالة:
خلية الحمل، الأردوينو، محول الإشارة التناظري إلى رقمي، أداة التكبير.